

## Solving Simultaneous **Nonlinear** Algebraic Equations

Larry Caretto  
 Mechanical Engineering 309  
**Numerical Analysis of Engineering Systems**  
 March 5, 2014

## Outline

- Problem Definition of solving simultaneous nonlinear algebraic equations (SNAE)
- Using the MATLAB `fsolve` function
- Using Excel Solver
- Excel Solver exercise
- Newton's Method (Newton-Raphson procedure) for solving SNAE

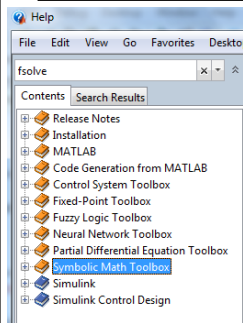
## Generalize Simple Example

- Two nonlinear equations in two variables
  - $2x - y - e^{-x} = 0$
  - $-x + 2y - e^{-y} = 0$
- How do we generalize this
  - Have N equations in N unknowns
  - Unknowns are labeled  $x_1, x_2, \dots, x_N$
  - Each equation is written in the form  $f_k = 0$
  - In general,  $f_k = f_k(x_1, x_2, \dots, x_N) = 0$ 
    - Many equations will not depend on all variables, but in general any equation could do so

## Problem Definition

- We consider a system of N equations in the N variables  $x_1, x_2, \dots, x_N$ 
  - The vector variable,  $\mathbf{x}$ , represents the set of unknowns  $[x_1, x_2, \dots, x_N]$
- The N equations have the form  $f_1(\mathbf{x}) = 0, f_2(\mathbf{x}) = 0, \dots, f_N(\mathbf{x}) = 0$ 
  - We can use the vector representation  $\mathbf{f}(\mathbf{x}) = \mathbf{0}$ , for the system of equations
    - Vector is  $\mathbf{f} = [f_1(\mathbf{x}), f_2(\mathbf{x}), \dots, f_N(\mathbf{x})]$
- We want to find the solution,  $\mathbf{x} = [x_1, x_2, \dots, x_N]$  to this set of equations

## MATLAB Components



- MATLAB has a basic system plus additional components called toolboxes
  - Extract from help window shows toolboxes on computers in JD 1126
    - Optimization toolbox, with function `fsolve` is not available

## MATLAB Function `fsolve`

- This MATLAB function to solve  $\mathbf{f}(\mathbf{x}) = \mathbf{0}$  is the multidimensional analog of `fzero`
- It has a similar function call
  - `<Results> = fsolve(<function>, <initial guess>, <options>)`
    - `<function>` returns the vector  $\mathbf{f}(\mathbf{x})$
    - `<initial guess>` is the vector  $\mathbf{x}_0$
  - Look at example
    - $f_1 = 2x_1 - x_2 - e^{-x_1} = 0$
    - $f_2 = -x_1 + 2x_2 - e^{-x_2} = 0$

### Using `fso1ve`

- Write the vector function to compute the values of the two equations  $f_1$  and  $f_2$   
function `F = testFct(x)`  
`F = ...`  
`[2*x(1) - x(2) - exp(-x(1)); ...`  
`-x(1) + 2*x(2) - exp(-x(2))];`  
`end %not required`
- Save this function file as `testFct.m` somewhere on your MATLAB path

### Using `fso1ve II`

- Define a for matrix for the initial guesses of  $x_1$  and  $x_2$ : `guess = [-5 -5]`
- Call the `fso1ve` function  
`>> fso1ve(@testFct, guess)`
- MATLAB uses the default variable, `ans`  
`ans = -0.5671 -0.5671`
- Test result by substituting into function  
`>> fva1 = testFct(ans)`  
`fva1 = -0.4059e-6 -0.4059e-6`

### More on `fso1ve`

- Third parameter, `<options>` used to set calculation options
  - Can set parameters such as convergence tolerance, iteration display, algorithm used
    - Typically use a routine, `optimset`, to set options
    - `opt=optimset('Display','iter');` %Sets option to display result of each iteration
- `fso1ve` has multiple outputs including, solution, function values, codes, etc.  
– `[x f flag out] = fso1ve(@myFunc, guess, opt)`

### Using Excel Solver

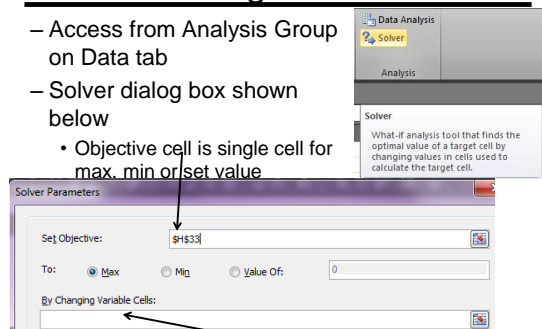
- Solver is a tool that varies selected cells to set a single cell to a fixed value a maximum value or a minimum value
- Main use is for constrained optimum (maximum or minimum problems)
- Can also be used for system of equations  $f_k(\mathbf{x}) = 0$  as shown on following slides
  - To do this create cells for all  $x_k$  and all  $f_k$  then a single cell to compute  $\sum_k f_k^2$

### Using Excel Solver II

- Solver is a tool that varies selected cells to set a single cell to a fixed value a maximum value or a minimum value
- Main use is for constrained optimum (maximum or minimum problems)
- Can also be used for system of equations  $f_k(\mathbf{x}) = 0$  as follows
  - Write each equation in a separate cell
  - Write one cell formula to compute  $\sum_k f_k^2$
  - Set cell with this formula equal to zero

### Using Solver

- Access from Analysis Group on Data tab
- Solver dialog box shown below
  - Objective cell is single cell for **max, min or set value**



### Solver Details for $f(\mathbf{x}) = \mathbf{0}$

- Enter each  $x_k$  value in a cell (usually in a single column)
  - Can use range names like x1\_ or x\_1
- Write a formula for each equation,  $f_k(\mathbf{x}) = 0$  in a cell (typically a single column)
- Create objection function cell with formula to obtain  $\sum_k f_k^2$
- Use solver to set objective function cell to zero by changing all  $x_k$  cells

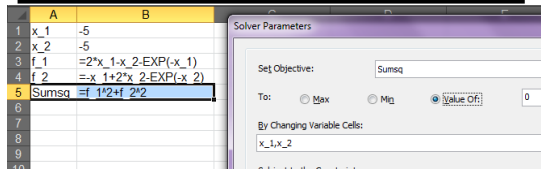
### Solver on fsolve Example

- Use previous example from fsolve:
  - $f_1 = 2x_1 - x_2 - e^{-x_1} = 0$
  - $f_2 = -x_1 + 2x_2 - e^{-x_2} = 0$
- With same initial guess  $x_1 = x_2 = -5$ 
  - Worksheet with initial conditions shown below in equation view

Cell names shown in Column A

	A	B
1	x_1	-5
2	x_2	-5
3	f_1	=2*x_1-x_2-EXP(-x_1)
4	f_2	=-x_1+2*x_2-EXP(-x_2)
5	Sumsq	=f_1^2+f_2^2

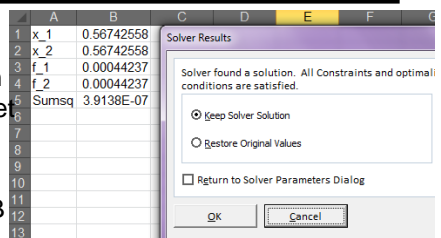
### Solver Entries for Example



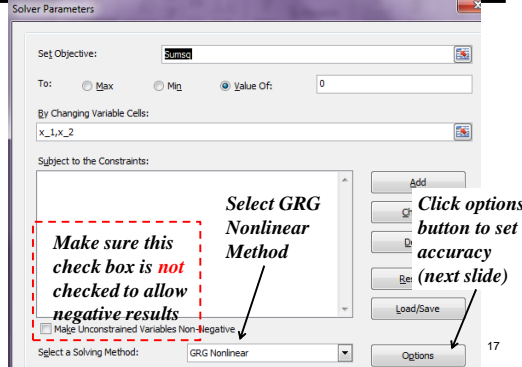
- Enter changing cells (with names  $x_1$  and  $x_2$ ) and objective cell (Sumsq)
- Select “Value Of:” and enter 0
- Click Solve at bottom of dialog

### Solver Result

- Results dialog on worksheet
- Solution shown in column B
- Click OK to accept solution or Cancel to return to original values
- If no result obtained retry with new initial  $x_k$



### Solver Settings



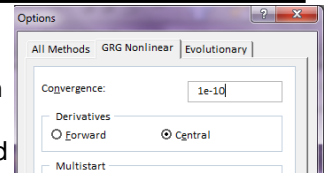
Make sure this check box is **not** checked to allow negative results

Select GRG Nonlinear Method

Click options button to set accuracy (next slide)

### Solver Accuracy

- Options dialog appears after Options button (previous slide) is clicked
- Set small number in Convergence box to give good accuracy in solution
- Click OK at bottom of Options dialog to exit that dialog



### Your Solver Exercise

- Use Solver to find the intersection of a straight line and a circle in the x-y plane
  - Line:  $y = mx + i$
  - Circle:  $(x - a)^2 + (y - b)^2 = r^2$
  - Use  $m = 1, i = -1, a = b = 1, r = 2$
  - Write as  $f_k(x,y) = 0, k = 1, 2$
  - $f_1 = y - mx - i = 0$
  - $f_2 = (x - a)^2 + (y - b)^2 - r^2 = 0$
  - Solver may not be able to find both solutions, but try different guesses

### Newton's Method for $f(\mathbf{x}) = \mathbf{0}$

- Use notation  $x_k^{(m)}$  and  $f_k^{(m)}$  for values of  $x_k$  and  $f_k$  at iteration  $m$
- Write Taylor series for  $f_k^{(m+1)}$  in terms of values at previous iteration:  $x_k^{(m)}, f_k^{(m)}$ 
  - Use only first-order terms
- $f_k^{(m+1)} = f_k^{(m)} + \sum_j \frac{\partial f_k}{\partial x_j} [x_j^{(m+1)} - x_j^{(m)}] + \dots$ 
  - Set  $f_k^{(m+1)} = 0$  for all  $f_k$  to get simultaneous linear algebraic equations:  $\mathbf{A}y = \mathbf{b}$

### How is this $\mathbf{A}y = \mathbf{b}$

- $-f_k^{(m)} = \sum_j \frac{\partial f_k}{\partial x_j} [x_j^{(m+1)} - x_j^{(m)}] + \text{Ignore higher-order terms}$
- $a_{kj} = \frac{\partial f_k}{\partial x_j} \quad b_k = -f_k^{(m)}$  and  $y_j = x_j^{(m+1)} - x_j^{(m)}$
- Partial derivative evaluated with values from iteration  $m$
- After  $y_j$  are found we have new set of  $x$  iterations as  $x_j^{(m+1)} = y_j + x_j^{(m)}$

### Return to fsolve Example

- Use previous example from fsolve:
 
$$f_1 = 2x_1 - x_2 - e^{-x_1} = 0$$

$$f_2 = -x_1 + 2x_2 - e^{-x_2} = 0$$

$$\frac{\partial f_1}{\partial x_1} = 2 + e^{-x_1} \quad \frac{\partial f_1}{\partial x_2} = -1$$

$$\frac{\partial f_2}{\partial x_1} = -1 \quad \frac{\partial f_2}{\partial x_2} = 2 + e^{-x_2}$$
- For each iteration we have to compute the  $\mathbf{A}$  matrix of partial derivatives and the  $\mathbf{b}$  vector of  $-f_j$ , and solve  $\mathbf{A}y = \mathbf{b}$  for the  $y$  and get  $x_j^{(m+1)} = y_j + x_j^{(m)}$

### Newton-Raphson Iteration Results

Each set of two rows has pattern shown in header

See NR workbook online

Iteration	x1	f1	df1/dx1	df1/dx2	y1
	x2	f2	df2/dx1	df2/dx2	y2
1	-5	-153.413	150.4132	-1	1.026771
	-5	-153.413	-1	150.4132	1.026771
2	-3.97323	-57.1291	55.15587	-1	1.054901
	-3.97323	-57.1291	-1	55.15587	1.054901
3	-2.91833	-21.4286	20.5103	-1	1.098324
	-2.91833	-21.4286	-1	20.5103	1.098324
4	-1.82	-7.99188	8.17188	-1	1.114336
	-1.82	-7.99188	-1	8.17188	1.114336
5	-0.70567	-2.73087	4.025198	-1	0.902706
	-0.70567	-2.73087	-1	4.025198	0.902706
6	0.197039	-0.62412	2.821159	-1	0.342705
	0.197039	-0.62412	-1	2.821159	0.342705
7	0.539744	-0.04315	2.582898	-1	0.027263
	0.539744	-0.04315	-1	2.582898	0.027263
8	0.567006	-0.00021	2.567221	-1	0.000137
	0.567006	-0.00021	-1	2.567221	0.000137
9	0.567143	-5.3E-09	2.567143	-1	3.4E-09
	0.567143	-5.3E-09	-1	2.567143	3.4E-09
10	0.567143	0	2.567143	-1	0
	0.567143	0	-1	2.567143	0

### Solution Hint

- Using Gaussian elimination on an exam or quiz is likely to have errors
  - You are more likely to get a better grade if you gave some simple indication of the operations you are doing

Here is an example

$$\begin{array}{rcccccc} 1 & -3 & 5 & 2 & 7 & \text{Row 1} \\ 0 & 1 & 6 & -1 & -2 & \text{Row 2} - (0/1)(\text{Row 1}) \\ 0 & 11 & -13 & 0 & -11 & \text{Row 3} - (2/1)(\text{Row 1}) \\ 0 & 19 & -34 & -13 & -32 & \text{Row 4} - (7/1)(\text{Row 1}) \end{array}$$

### Quiz five

$$\begin{array}{l} w + 2x - y + 3z = 5 \\ 2w - 3x + 5y - 2z = 9 \\ 4w + 4x - 2y + z = 13 \\ 5w - 8x + 11y - 12z = 16 \end{array} \quad \begin{array}{l} w + 2x - y + 3z = -5 \\ 2w - 3x + 5y - 2z = 20 \\ 4w + 4x - 2y + z = 4 \\ 5w - 8x + 11y - 12z = 60 \end{array}$$

Write two sets of equations above as augmented matrix at right and take first step below

$$\begin{array}{cccccc} 1 & 2 & -1 & 3 & 5 & -5 \\ 2 & -3 & 5 & -2 & 9 & 20 \\ 4 & 4 & -2 & 1 & 13 & 4 \\ 5 & -8 & 11 & -12 & 16 & 60 \end{array}$$

### Quiz five II

Results of first row as pivot row at right and use of second row as pivot row shown below

$$\begin{array}{cccccc} 1 & 2 & -1 & 3 & 5 & -5 \\ 0 & -7 & 7 & -8 & -1 & 30 \\ 0 & -4 & 2 & -11 & -7 & 24 \\ 0 & -18 & 16 & -27 & -9 & 85 \end{array}$$

### Quiz Five Solution II

- After row 2 as pivot row

$$\begin{array}{rcccccc} 1 & -3 & 5 & 2 & 7 & \text{Row 1} \\ 0 & 1 & 6 & -1 & -2 & \text{Row 2} \\ 0 & 0 & -79 & 11 & 11 & \text{Row 3} - (11/1)(\text{Row 2}) \\ 0 & 0 & -148 & 6 & 6 & \text{Row 4} - (19/1)(\text{Row 2}) \end{array}$$

Using row 3 as pivot subtract  $-148/(-79)$  times row 3 from row to give

$$\begin{array}{rcccccc} 0 & 0 & 0 & -14.6076 & -14.6076 & \text{Row 4} \end{array}$$

### Backsubstitution

$$\begin{array}{r} w + -3x + 5y + \quad \quad 2z = \quad \quad 7 \\ \quad \quad x + 6y + \quad \quad -1z = \quad \quad -2 \\ \quad \quad -79y + \quad \quad 11z = \quad \quad 11 \\ \quad \quad \quad \quad -14.6076z = -14.6076 \end{array}$$

$$\begin{aligned} z &= -14.6076/(-14.6076) = 1 \\ y &= (11 - 11z)/(-79) = [11 - 11(1)]/(-79) = 0 \\ x &= [-2 + z - 6y]/1 = [-2 + 1 - 6(0)]/1 = -1 \\ w &= [7 - 2z - 5y + 3x]/1 = [7 - 2(1) - 5(0) + 3(-1)]/1 = 2 \end{aligned}$$