## A Characterization of First Order Phase Transitions for Superstable Interactions in Classical Statistical Mechanics (Extended Version)

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Abstract.We give bounds on finite volume expectations for a set of boundary conditions containing the support of any tempered Gibbs state and prove a theorem connecting the behavior of Gibbs states to the differentiability of the pressure for continuum statistical mechanical systems with long range superstable potentials. Convergence of grandcanonical Gibbs states is also studied.

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### **1. Introduction**

For a grandcanonical system of particles, a first order phase transition is said to occur if the pressure is not continuously differentiable with respect to chemical potential. First order phase transitions are also generally associated with multiple infinite volume Gibbs states. The existence of multiple Gibbs states, however, does not imply a first order phase transition, as can be seen in the case of the two dimensional Ising antiferromagnet (or, more appropriately, the equivalent lattice gas)<sup>14</sup>. Rigorous connections between the behavior of Gibbs states and the differentiability of the pressure or free energy with respect to various parameters have been made by a number of authors; we mention only a few. Lebowitz and Martin-Lof<sup>1</sup> proved for Ising ferromagnets, that the free energy is differentiable with respect to the external field if and only if the Gibbs state is unique. Lebowitz and Presutti<sup>2</sup> generalized this result for unbounded spin spaces. Related work was done for attractive specifications by Preston<sup>3</sup>. Lebowitz in Refs.4, 5 proved, among other results, that differentiability of the free energy with respect to the inverse temperature implies that only two translation invariant extremal Gibbs states can coexist below the critical point for a large class of lattice ferromagnets. Lanford and Ruelle<sup>6</sup> identified translation invariant Gibbs states with the tangent functionals to the pressure on a Banach

space of Hamiltonians (for expositions, additional references, and extensions, see Refs. 6, 2). For a class of lattice models, Ruelle<sup>8</sup> established a connection between the existence of non-translation invariant Gibbs states and the differentiability of the pressure in the direction of a nontranslation invariant external field.

In this paper we consider long range, superstable interactions in **R**<sup>d</sup>. We prove that a first order phase transition occurs at a point in phase space if and only if multiple, translation invariant, tempered Gibbs states exist at that point and they yield strictly different expectations for the density of particles. An analogous statement is proven for differentiation with respect to the inverse temperature. Our results therefore extend to a broad class of continuum models a rigorous mathematical connection between two widely used criteria to establish phase transitions. To prove the main theorem we show how finite volume expectations of particle density and energy may be bounded in the presence of an arbitrary external configuration in the support set of any tempered Gibbs state. We also prove a convergence result for grandcanonical, tempered Gibbs states when the respective temperatures or chemical potentials converge.

We note that the conclusions of our main theorem are known for a large class of lattice models with compact configuration space and bounded Hamiltonians (c.f. Refs. 6, 7, 3). The methods used in those references are not available here since our Hamiltonians are unbounded and configurations of particles may have arbitrarily large local densities. Instead we use measure-theoretic techniques and especially the probability estimates of Ruelle<sup>9</sup>. Lebowitz and Presutti<sup>2</sup> obtained somewhat related results, using different methods, for models with unbounded spin spaces, but the conditions they impose on the Hamiltonian are not satisfied by the usual models of classical continuum statistical mechanics.

Definitions are given in Sect. 2; section 3 contains our main results.

#### 2. Notation and Preliminary Results

For a Borel measurable subset  $\mathbf{R}^d$ , let X( ) denote the set of all locally finite subsets of . X( ) represents configurations of identical particles in . We let denote the empty configuration. Let B be the -field on X( ) generated by all sets of the form {s X( ): |s | =m}, where B runs over all bounded Borel subsets of , m runs over the set of nonnegative integers, and  $|\cdot|$  denotes cardinality. We let ( , S) = (X( $\mathbf{R}^d$ ), B<sub>R</sub>d). For a configuration x , let x = x .

A Hamiltonian H is an S measurable map from the set of finite configurations  $_{\rm F}$  in to (- , ] of the form

$$H(x) = (x^{i}, x^{j}) - h|x|$$
(2.1)

where the function is a pair potential and where h **R**. The configuration x in (2.1) is coordinatized by  $x = \{x^1, x^2, ..., x^{|x|}\}$ . For x X(), we will sometimes write H (x) instead of H(x).

For a bounded Borel set , let | | denote the Lebesgue measure of . The symbol | | may therefore represent cardinality or Lebesgue measure, but the meaning will always be clear from the context.

Define the interaction energy between x X() and s <sup>c</sup> by  

$$W(x|s) = \prod_{i=1}^{n} (x^{i}, s^{j})$$
(2.2)

where  $x = \{x^1, ..., x^n\}$ , and s  $c = \{s^1, ..., s^m\}$  We will sometimes write

W(x | s) when x and s are located in disjoint regions. Define

H 
$$(x | s) = H (x) + W (x | s)$$
 (2.3)

For each i  $\mathbf{Z}^{d}$ , let

$$Q_i = \{r \ R^d: r^k - 1/2 \ i^k < r^k + 1/2, k=1,...,d\}$$

so that the unit cubes  $\{Q_i\}$  partition  $\mathbb{R}^d$ . Define  $|x_i| |x_{Q_i}| = |x - Q_i|$ . For a nonnegative integer k, let  $_k$  be the hypercube of length 2k - 1 centered at the origin in  $\mathbb{R}^d$ ;  $_k$  is then a union of  $(2k - 1)^d$  unit cubes of the form  $Q_i$ . We will also sometimes regard  $_k$  as a subset

of  $\mathbf{Z}^d$  by letting k represent k  $\mathbf{Z}^d$ .

For i  $\mathbf{Z}^d$  or  $\mathbf{R}^d$ , let  $||i|| = ||(i^1,...,i^d)|| = \max_k |i^k|$  be the supnorm.

We assume throughout this paper that H satisfies the following conditions:

a) , are translation invariant

b) H is superstable<sup>9,10</sup>, i.e., there exist A>0, B 0 such that if the configuration x is contained in  $_{k}$  for some k, then

H(x) 
$$A|x_i|^2 - B|x_i|$$
 (2.4)

(Note that if A is allowed to be zero in (2.4), H(x) is said to be stable.)

c) H(x) is lower regular. There exists a positive function on the nonnegative integers such that (m) Km<sup>-</sup> for m 1, and for any 1 and 2 which are each finite unions of unit cubes of the form  $Q_i$ , with x 1 and s 2,

$$W(x | s) - (||i-j||) |x_i| |s_j|$$
(2.5)

where K > 0, > d are fixed.

d) H(x) is tempered. There exists  $R_0 > 0$  such that with the same notation as in part c, assuming 1 and 2 are separated by a distance  $R_0$  or more,

W (x | s) K 
$$|i-j|| = |x_i| |s_j|$$
 (2.6)

Temperedness and lower regularity allow W(x|s) to be defined when s is an infinite configuration of particles. Collections of appropriate infinite configurations are described below. We note that without loss of generality the conditions on H(x) may be modified by replacing each of the unit cubes  $Q_i$  by cubes with any preassigned volume.

We next define a measure for each bounded Borel set of  $\mathbf{R}^d$ . Let  $X_N() X()$  be the set of configurations of cardinality N in and let T:  $N X_N()$  be the map which takes the ordered N-tuple  $(x_1, \ldots, x_N)$  to the (unordered) set  $\{x_1, \ldots, x_N\}$ . In a natural way T defines an equivalence relation on  ${}^N$  and  $X_N(\ )$  may be regarded as the set of equivalence classes induced by T. For N = 1, 2, 3, ..., let  $d^N x$  be the projection of nd-dimensional Lebesgue measure onto  $X_N(\ )$  under the projection T:  ${}^N X_N(\ )$ . The measure  $d^o x$  assigns mass 1 to  $X_0(\ ) = \{\ \}$ . Define  $d^N x$  to be the zero measure on  $X_M(\ )$  for M N. On X( ) =  $\bigcup_{n=0}^{n} X_n(\ )$ 

$$(\mathrm{d}\mathbf{x}) = \frac{\mathrm{d}^{\mathrm{n}}\mathbf{x}}{\mathrm{n}!}$$

If A = where and A are Borel sets, then

 $(X( ), B , ) \times (X(A), B_A, A)$  may be identified with  $(X( A), B_A, A)$  via x  $\times x_A = x$   $x_A$ . In particular, for any bounded Borel set ,

$$(, S) = (X(), B) \times (X(^{c}), B c)$$
 (2.7)

Let  $\tilde{B}$  denote the inverse projection of B under the identification (2.7) so that  $\tilde{B}$  is a -field on .

Let be a bounded Borel set in  $\mathbb{R}^d$  and let s be a configuration in <sup>c</sup>. The finite volume Gibbs state with boundary configuration s for H,  $> \Omega$  and h is

$$\mu (dx|s) = \frac{\exp\{-H(x|s)\}}{Z(s)} (dx)$$
(2.8)

where Z (s) Z ( ,h,s) makes  $\mu$  (dx|s) a probability measure and is inverse temperature. When s = , let  $\mu$  (dx| )  $\mu$  (dx).

Definition 2.1 The pressure p( , h) for H is given by

$$P(, h) = \lim_{k} \frac{\ln Z_{k}()}{|_{k}|}$$
(2.9)

where P(, h) = p(, h)

*Remark 2.1* The limit in (2.9) is well-known to exist<sup>9,10</sup> and to be a convex function of and h for the models that we consider, and it is also possible to consider more general

limits than described above, but this is as much as we will need. We note some general properties of convex functions on intervals which we will use later: Derivatives exist except possibly at countably many points. Right and left hand derivatives exist at every point, and the left hand derivative at a point  $x_0$  is no larger than the right hand derivative at  $x_0$ . If the derivative of a convex function exists at a point, then the derivative is continuous at that point. If P is a convex function differentiable at  $_0$  and if P<sub>n</sub> are convex and differentiable at  $_0$  with P<sub>n</sub>() P() pointwise, then P<sub>n</sub>'( $_0$ ) P'( $_0$ ).

Let { } denote the specification associated with , h and the Hamiltonian H (see Preston<sup>3</sup> [pg 16] defined by

$$(A | s) = A' \mu (dx|s)$$
 (2.10)

where  $A' = \{x \ X() : x \ s \ A\}$ . This specification is defined with respect to the sets  $\{R\}$  as defined by Preston and is consistent<sup>3</sup>.

A probability measure  $\mu$  on  $\;$  is a Gibbs state (or infinite volume Gibbs state) for H,  $\;$  , and h if

$$\mu \left( (A \mid s) \right) = \mu(A)$$

for every A S and every bounded Borel set .

A function f: $\mathbf{R}$  is a cylinder function if there exists a finite volumesuch thatf(s) = f(s) for all s. A set AS is a cylinder set if the indicator function for A is acylinder function.

Following Ruelle<sup>9</sup> we define a Gibbs state  $\mu$  to be tempered if  $\mu$  is supported on

$$V = \bigcup_{N=1} V_N$$

where  $V_N = \{x : |x_i|^2 | N^2 | k | \text{ for all } k \}$ . The following proposition collects some results proved by Ruelle in Ref. 9.

 and h (independent of  $\tilde{}$  and ) such that the probability that |x | N| | with respect to  $\mu_{-}(dx|)$  is less than  $exp[-(N^{2} - )| |]$ . The same probability estimate holds when  $\mu_{-}(dx|)$  is replaced by any tempered Gibbs state for h. Moreover, for any h, the set of translation-invariant, tempered Gibbs states is nonempty.

With Proposition 2.1, it is possible to describe another support set for tempered Gibbs states. Let  $ln_+r = max\{1, ln r\}$ . Define

$$U_{n} = \{s : |s_{i}| \quad n \ \sqrt{\ln_{+}} ||i|| \text{ for all } i \quad \mathbb{Z}^{d} \}$$
$$U = \bigcup_{n=1} U_{n} \qquad (2.11)$$

A straightforward argument<sup>2,11</sup> shows that  $\mu(U) = 1$  for any tempered Gibbs state  $\mu$ .

The following lemma will be used to control the effect of boundary configurations on certain expected values in the next section.

**Lemma 2.1** Let > 0 and s U<sub>n</sub>. Then for all k sufficiently large,

a.  $W_{k}(x|s) - D_{k}(s) |x_{k}| - n |x_{m}|$ b.  $|W_{k}(x_{m}|s)| - n |x_{m}|$ 

where m is the greatest integer k - C  $(\ln k)^{1/(-d)}$ , C is a constant for each independent of k,  $k = k \mid m$ , and  $D_k(s) \mid C \mid \sqrt{\ln k}$  for some constant C. *proof.* For simplicity, we write k = -. By lower regularity,

$$W_{_k}(x|s) \qquad -K_{_{i_{_k}j_{_k}c_k}} ||i-j|| - |x_i| |s_j|$$

$$-K \mid x \quad \mid \max_{i} \quad \underset{j \quad c_{k}}{ } \quad \mid |i-j|| \quad - \quad |s_{j}| \quad -K \quad \mid x \quad \underset{m}{ } \mid \max_{i} \quad \underset{m}{ } \quad \underset{j \quad c_{k}}{ } \quad \mid |i-j|| \quad - \quad |s_{j}| \quad - \quad |s_{j}$$

We first show

$$D_k(s) \quad \underset{i}{\operatorname{Kmax}} \underset{j \quad {}_k}{\operatorname{Kmax}} ||i-j|| - |s_j| \quad C \text{ n } \sqrt{\ln k}$$

Since s U<sub>n</sub>,

$$D_{k}(s) \quad n \underset{i}{K} \max_{j} ||i-j|| - \sqrt{\ln ||j||}$$
(2.12)

Let  $i_0$  maximize the sum in (2.12) so that

$$D_k(s) \quad n \ K \qquad \qquad \|i_0 - j\| \ - \ \sqrt{\ln \, ||j||}$$

With  $\ell = j - i_0$ ,

$$\begin{array}{cccc} D_{k}(s) & n \ K & || \ \ell \ || \ - & \sqrt{\ln (|| \ \ell || + || i_{o}||)} \\ n \ K & || \ \ell \ || \ - & \sqrt{\ln (e|| \ \ell ||) + \ln k} \\ n \ K & \sqrt{\ln k} & || \ \ell \ || \ - & \sqrt{\ln (e^{2} || \ \ell ||)} \\ C \ n \ \sqrt{\ln k} & \end{array}$$

We next show that with an appropriate choice of C,

 $K \max_{i = m \atop j = 0} ||i-j|| - |s_j| = n$  (2.13)

for all k sufficiently large.

where  $i_0$  maximizes the sum in (2.14). With  $\ell = j - i_0$  and C(d) a constant for dimension d,

$$K \max_{i = m} ||i-j|| - ||s_j| = n K ||\ell|| - \sqrt{\ln (||\ell|| + m)}$$

$$n K ||\ell|| - \sqrt{\ln ||\ell|| + m}$$

$$n K \sqrt{||\ell|| - \sqrt{\ln ||\ell|| + m}}$$

$$n K \sqrt{\ln m} ||\ell|| - \sqrt{\ln ||\ell||} \ln m$$

$$||\ell|| - \sqrt{\ln ||\ell||}$$

$$n C(d) \sqrt{\ln m} C^{-\frac{-d}{2}} 2(-d)^{-1} (2.15)$$

where C is chosen so that C(d)  $C^{\frac{-d}{2}} 2(-d)^{-1} < .$  Thus part a is proved. To obtain the lower bound in part b, observe that from part a,

$$W_{k}(x = |s|) - D_{k}(s) | |- n|x_{m}| = - n|x_{m}|$$

The upper bound for W  $_{_k}(x - _m|s)$  is similarly established from the fact that the

Hamiltonian is tempered and that the distance between  ${}^{c}_{k}$  and  ${}_{m}$  is larger than  $R_{o}$  for sufficiently large k.

*Remark* 2.2 It follows from the proof of Lemma 2.1 that  $W_{k}(x|s) - D_{k}(s) |x_{k}|$  for all k, by redefining k = 0, m = 0.

For the convenience of the reader we conclude this section with two known results from measure theory which we will use in the next section. The first is a generalization of the Lebesgue Dominated Convergence Theorem [c.f. Royden<sup>12</sup>].

**Proposition 2.2** Let (X,B) be a measurable space and  $\{\mu_n\}$  a sequence of measures on B that converge setwise to a measure  $\mu$ . Let  $\{f_n\}$  be a sequence of measurable functions converging pointwise to f. Suppose  $|f_n|$  g and that  $\lim_{n \to \infty} gd\mu_n = g d\mu < \cdot$ . Then

$$\lim_{n} f_{n} d\mu_{n} = f d\mu$$

A measurable space (X,B) is a standard Borel space if there exists a complete metric space Y such that B is -isomorphic to the Borel -field B<sub>Y</sub> of Y, i.e., there is a bijection from B to B<sub>Y</sub> which preserves countable set operations. The measurable spaces ( , S) and (X( ), B ) considered in this paper are standard Borel spaces. The following proposition has been used by Parthasarathy Ref.13 pg 145 and Preston in Ref. 2 pg 27. We provide a short proof for convenience to the reader.

**Proposition 2.3** Let X be uncountable and (X,B) a standard Borel space. There exists a countable field  $B_0$  B such that  $B = (B_0)$  and such that if  $\mu$ :  $B_0$  [0,1] is a finitely additive probability measure on  $B_0$ , then  $\mu$  has a unique extension to a (countably additive) probability measure on (X,B).

*proof.* (X,B) is isomorphic as a measure space to  $_{i=1}^{\{0,1\}}$  with the product Borel -field. Let B<sub>n</sub> be the finite -field generated by the first n factors. Then  $\bigcup_{n=1}^{n} B_n$  is a countable field. Any finitely additive probability measure on  $\bigcup_{n=1}^{n} B_n$  is consistent on  $\{B_n\}$ . The result now follows by the Kolmogorov extension theorem.

# **3. Principal Results**

**Lemma 3.1** There exist functions  $g_1$ ,  $g_2$ ,  $g_3$  on U , integrable with respect to any tempered Gibbs state such that for all k sufficiently large,

a. 
$$\frac{1}{\begin{vmatrix} k \\ k \end{vmatrix}} \begin{vmatrix} x \\ k \end{vmatrix} \mu_{k}(dx|s) \leq g_{1}(s)$$
  
b. 
$$\frac{1}{\begin{vmatrix} k \\ k \end{vmatrix}} \begin{vmatrix} W_{k}(x|s) \mu_{k}(dx|s) \end{vmatrix} \leq g_{2}(s)$$
  
c. 
$$\frac{1}{\begin{vmatrix} k \\ k \end{vmatrix}} \mid H_{k}(x|s) \mu_{k}(dx|s) \end{vmatrix} \leq g_{3}(s)$$

*Remark 3.1* The integrable bounds in Lemma 3.1 may be chosen to hold for all k; we find bounds only for all large values of k in order to streamline the proof.

*proof.* Observe that for any function f on X(k),

$$f(x) \mu_{k}(dx|s) = \frac{f(x) e^{-W_{k}(x|s)} \mu_{k}(dx)}{e^{-W_{k}(x|s)} \mu_{k}(dx)}$$
(3.1)

Let > 0 and s  $U_n$ . In what follows we identify k, m, and k, as in

k

Lemma 2.1. Let

$$(\mathbf{x}) = \frac{1 \text{ if } \mathbf{x}_{m}}{0 \text{ otherwise}}$$
(3.2)

Then using the product structure of

 $e^{-W_{k}(x|s)} \mu_{k}(dx) = (x)e^{-W_{k}(x|s)} \mu_{k}(dx)$ 

$$= \frac{1}{Z_{k}(-)} (x) e^{-W_{k}(x|s)} e^{-H_{k}(x)} e^{-H_{k}(x)} (dx)$$

$$= \frac{1}{Z_{k}(-)} e^{-W_{k}(x|s-c_{k})} e^{-H_{m}(x)} (dx) e^{-H_{m}(x)} (dx) e^{-M_{k}(x)} e^{-M$$

Therefore by Jensen's inequality,

$$\ln e^{-W_{k}(x|s)} \mu_{k}(dx) - n |x_{m}| \mu_{m}(dx) + \ln Z_{m}() - \ln Z_{k}()$$
(3.3)

We next bound  $|\mathbf{x}_{m}| \boldsymbol{\mu}_{m}(d\mathbf{x})$  using Ruelle's probability estimates (Prop. 2.1).

$$\frac{1}{||\mathbf{m}||} ||\mathbf{x}_{m}||\boldsymbol{\mu}_{m}(d\mathbf{x}) = {}_{0}\boldsymbol{\mu}_{m}\{\mathbf{x}_{m}:|\mathbf{x}_{m}| > \mathbf{y}|_{m}|\}d\mathbf{y}$$

$$\int_{0}^{\mathbf{F}} 1d\mathbf{y} + {}_{\mathbf{F}} \exp\{-(|\mathbf{y}^{2} - |\mathbf{y}|_{m}|\}d\mathbf{y}$$

$$\int_{-}^{\mathbf{F}} + {}_{\mathbf{F}} \exp\{-||\mathbf{m}|(\mathbf{y} - \sqrt{-})^{2}\}d\mathbf{y}$$

$$\int_{-}^{\mathbf{F}} + \sqrt{\frac{4}{4}} ||\mathbf{m}||$$
(3.4)

where and are the constants appearing in Proposition 2.1. Since |k| > |m|, (3.3) and (3.4) give,

$$\ln e^{-W_{k}(x|s)} \mu_{k}(dx) \ge -n \sqrt{-|k|} + \sqrt{\frac{|k|}{4}} + \ln Z_{m}(x) - \ln Z_{k}(x)$$
(3.5)

To bound the numerator in (3.1), observe that for any c > 0, and any union of unit cubes in  $_k$ ,

$$e^{c|x|} \mu_{k}(dx) = {}_{0}\mu_{k}\{x_{k}: e^{c|x|} > y\}dy$$

$$< \exp[(2c^{2}| |) / ] + \exp[| |-(2c^{2}| |) / ]$$
  
$$< 2\exp[(+2c^{2} / |) |]$$
(3.6)

For any a 0, it follows from (3.6) and Lemma 2.1 that

$$e^{a|x|} e^{-W_{k}(x|s)} \mu_{k}(dx) = e^{D_{k}(s)|x|} e^{(n+a)|x|} \mu_{k}(dx)$$

$$\left(e^{2D_{k}(s)|x|} \mu_{k}(dx)\right)^{1/2} \left(e^{2(-n+a)|x|} \mu_{k}(dx)\right)^{1/2}$$

$$2exp\left[\left(\frac{8^{-2}D_{k}(s)^{2}}{2} + 1\right) - 1\right]^{1/2} 2exp\left[\left(\frac{8(-n+a)^{2}}{2} + 1\right) - 1\right]^{1/2}$$

$$= 2exp\left[\left(\frac{4^{-2}D_{k}(s)^{2}}{2} + \frac{1}{2}\right) - 1 + \left(\frac{4(-n+a)^{2}}{2} + \frac{1}{2}\right) - 1\right]^{1/2}$$

$$(3.7)$$

Using Jensen's inequality and (3.1) gives

$$|x_{k}| \mu_{k}(dx|s) = \ln e^{|x_{k}|} \mu_{k}(dx|s)$$

$$\ln e^{|x|} e^{-W_{k}(x|s)} \mu_{k}(dx) - \ln e^{-W_{k}(x|s)} \mu_{k}(dx)$$
(3.8)

Combining (3.8) with (3.5) and (3.7) with a = 1 gives

$$\frac{1}{\begin{vmatrix} k \end{vmatrix}} \begin{vmatrix} x \\ k \end{vmatrix} = \frac{4^{-2}D_{k}(s)^{2}}{2} + \frac{1}{2} \begin{vmatrix} k \\ k \end{vmatrix} + \frac{4(n+1)^{2}}{2} + \frac{1}{2} + \frac{\ln 2}{\left| k \right|} + \frac{1}{2} + \frac{\ln 2}{\left| k \right|} + \frac{1}{2} + \frac{1}{2} + \frac{\ln 2}{\left| k \right|} + \frac{1}{2} +$$

$$+ n \sqrt{-} + \sqrt{\frac{4}{4} \left|_{k}\right|} - \frac{1}{\left|_{k}\right|} \frac{m}{m} \ln Z_{m}() + \frac{1}{\left|_{k}\right|} \ln Z_{k}() \qquad (3.9)$$

By Lemma 2.1  $D_k(s)$  C n  $\sqrt{\ln k}$ . Therefore the right side of (3.9) is a quadratic polynomial in n:

$$C_{2}(k) n^{2} + C_{1}(k) n + C_{0}(k),$$
  
where 0  $C_{i}$  sup<sub>k</sub>  $C_{i}(k) <$  for  $i = 0,1,2$  and  
n n(s) min{m  $\mathbb{Z} : s \ U_{m}$ } (3.10)

Define with (3.10)

$$g_1(s) = C_2 n^2 + C_1 n + C_0$$

If 
$$\mu$$
 is a tempered Gibbs state, it is easy to show, using Proposition 2.1 that there exists a constant D such that

$$\mu(U_{m}^{c}) \quad D \exp[-m^{2}]$$
 (3.11)

for all m sufficiently large. Thus

$$g_1(s) \mu(ds) = \sum_{i=0}^{2} C_i m^i \mu(U_{m-1}^c) < (3.12)$$

This proves part a of Lemma 3.1.

To prove part b observe that by Lemma 2.1,  

$$\frac{1}{\begin{vmatrix} k \end{vmatrix}} = W_{k}(x|s) \mu_{k}(dx|s) - \frac{1}{\begin{vmatrix} k \end{vmatrix}} D_{k}(s)|x| + \mu_{k}(dx|s) - \frac{|x_{k}|}{|x_{k}|} \mu_{k}(dx|s)$$
(3.13)

From part a, the second integral on the right is bounded below by  $-g_1(s)$ . To bound the first integral on the right side of (3.13) notice that by Jensen's inequality and (3.1)

$$D_{k}(s)|x | \mu_{k}(dx|s) \ln e^{D_{k}(s)|x |} \mu_{k}(dx|s)$$

$$\ln e^{D_{k}(s)|x |} e^{-W_{k}(x|s)} \mu_{k}(dx) - \ln e^{-W_{k}(x|s)} \mu_{k}(dx)$$
(3.14)

Applying (3.5), (3.6), and Lemma 2.1 as before shows that the right side of (3.14) is

bounded by a polynomial in n(s) which is integrable with respect to any tempered Gibbs state.

On the other hand, by Jensen's inequality and (3.1),

W

$$= \ln \frac{e^{+ |W_{k}(x|s)|} \mu_{k}(dx|s)}{e^{- |W_{k}(x|s)|} \mu_{k}(dx)}$$

$$= \ln \frac{e^{+ |W_{k}(x|s)|} e^{- |W_{k}(x|s)|} \mu_{k}(dx)}{e^{- |W_{k}(x|s)|} \mu_{k}(dx)}$$

$$= -\ln |e^{- |W_{k}(x|s)|} \mu_{k}(dx)$$

$$n \sqrt{-|K_{k}|} + \sqrt{\frac{|K_{k}|}{4}} - \ln Z_{m}(x) + \ln Z_{k}(x) \qquad (3.15)$$

where the last inequality comes from (3.5). Dividing both sides of (3.15) by |k| shows that

$$\frac{1}{\begin{vmatrix} k \end{vmatrix}} \quad W_{k}(x|s) \ \mu_{k}(dx|s)$$

is bounded above by a linear function in n(s) with coefficients bounded in k. Hence it is bounded by a function  $g_2(s)$  integrable with respect to any tempered Gibbs state.

By stability of H(x),  

$$\frac{1}{\begin{vmatrix} k \end{vmatrix}} = H_{k}(x|s) \mu_{k}(dx|s) = \frac{1}{\begin{vmatrix} k \end{vmatrix}} = -B|x| + W_{k}(x|s) \mu_{k}(dx|s)$$
(3.16)

The integral on the right is bounded below by a linear combination of the functions  $g_1(s)$  and  $g_2(s)$  from parts a and b.

To find an upper bound, write

 $H_{k}(x|s) \mu_{k}(dx|s) = \ln_{k} e^{H_{k}(x|s)} \mu_{k}(dx|s)$ 

$$= \ln \frac{e^{+H_{k}(x|s)}e^{-W_{k}(x|s)}\mu_{k}(dx)}{e^{-W_{k}(x|s)}\mu_{k}(dx)}$$

$$= \ln \frac{e^{+H_{k}(x)} e^{-H_{k}(x)}}{Z_{k}(-) e^{-W_{k}(x|s)} \mu_{k}(dx)}$$

$$= \ln \frac{e^{|k|}}{Z_{k}(-) e^{-W_{k}(x|s)} \mu_{k}(dx)}$$

$$n \sqrt{-|k|} + \sqrt{\frac{|k|}{4}} - \ln Z_{m}(-) + |k|$$
(3.17)

where in the last inequality we have used (3.5). Dividing both sides (3.17) by  $|_{k}$  shows that

$$\frac{1}{\left| {}_{k} \right|} \left| H_{k}(x|s) \mu_{k}(dx|s) \right|$$
(3.18)

is bounded by a linear function of n(s) with coefficients bounded in k and (3.18) is therefore bounded by an integrable function of s.

Lemma 3.2 a) For any s U

$$\lim_{k} \frac{W_{k}(x|s)}{|x|} \mu_{k}(dx|s) = 0$$

b) For any tempered Gibbs state  $\mu$ 

$$\lim_{k} \frac{W(x_{k}|x_{c})}{|x_{k}|} \mu(dx) = 0$$

proof. Since

$$W(x_{k}|x_{k})\mu(dx) = W_{k}(x|s)\mu_{k}(dx|s)\mu(ds)$$

part b follows from part a, Lemma 3.1b, and the Dominated Convergence Theorem.

From (3.15)

$$\lim_{k} \sup \frac{W_{k}(x|s)}{|x|} \mu_{k}(dx|s) = n(s) (1/2)^{1/2}$$
(3.19)

where we have used the same notation as in the proof of Lemma 3.1. Since > 0 is arbitrary,

$$\lim_{k} \sup \frac{W_{k}(x|s)}{|x|} \mu_{k}(dx|s) = 0$$
(3.20)

From (3.5), (3.13), (3.14), and Lemma 3.1a

$$W_{k}(x|s) \mu_{k}(dx|s) - g_{1}(s)|_{k}| - \ln e^{D_{k}(s)|x|} e^{-W_{k}(x|s)} \mu_{k}(dx)$$
$$- n \sqrt{-}|_{k}| + \sqrt{\frac{|_{k}|}{4}} + \ln Z_{m}() - \ln Z_{k}() \quad (3.21)$$

It is necessary to bound the integral on the right side of (3.21) differently than in the proof of Lemma 3.1.

$$e^{D_k(s)|x|}e^{-W_k(x|s)}\mu_k(dx) = e^{(+1)D_k(s)|x|}e^{n|x_k|}\mu_k(dx)$$

$$= e^{(+1)D_{k}(s)|x|} \tilde{\mu}_{k}(dx) \frac{Z_{k}(,h+n,)}{Z_{k}(,h,)}$$
(3.22)

where  $\tilde{\mu}_{k}$  is the finite volume Gibbs state for s = - and h replaced by h+ - n. By (3.6)

$$e^{D_{k}(s)|x|} e^{-W_{k}(x|s)} \mu_{k}(dx) = 2exp = \frac{2(+1)^{2}D_{k}(s)^{2}}{\tilde{x}} + \left| - \right| \frac{Z_{k}(,h+n,)}{Z_{k}(,h,)}$$
(3.23)

where  $\tilde{}$  and  $\tilde{}$  are the constants from Prop. 2.1 for h replaced by h + n. Combining (3.23) and (3.21) gives

$$\frac{W(x_{k}|s)}{|k|} \mu_{k}(dx|s) - n \sqrt{-} + \sqrt{\frac{2}{2}|k|} + \frac{|m|}{|k|} \frac{1}{|m|} \ln Z_{m}(-) - g_{1}(s)$$
$$- \frac{2(-+1)^{2}D_{k}(s)^{2}}{-} + \frac{|m|}{|k|} - \frac{\ln 2}{|k|} - \frac{\ln 2}{|k|} \ln Z_{k}(-, h + -n, -)$$
(3.24)

Therefore,

$$\lim_{k} \inf \frac{W(x_{k}|s)}{|x_{k}|} \mu_{k}(dx|s) - n(s)(/)^{1/2} - g_{1}(s) + P(,h) - P(,h+n)$$
(3.25)

By continuity of the pressure [c.f. Ruelle<sup>10</sup>] in h and since > 0 is arbitrary,

$$\lim_{k} \inf \frac{W(x_{k}|s)}{|x_{k}|} \mu_{k}(dx|s) = 0$$
(3.26)

Inequalities (3.20) and (3.26) establish part b.

It is well known that the limit P(, h) in (2.9) is unchanged if the empty configuration in Z () is replaced by an arbitrary configuration s for standard lattice models (see for example Refs. 7,2). In Corollary 3.1 below, we prove that this is also the case for our continuum models, provided that the configuration s U.

**Corollary 3.1** For any s U , 
$$\lim_{k} \frac{\ln Z_{k}(s)}{|k|} = P(k,h)$$

proof. For any k,

$$Z_{k}() = \frac{e^{+W_{k}(x|s)}}{X_{k}(x)} \frac{e^{-H_{k}(x|s)}}{Z_{k}(s)} - \frac{e^{-H_{k}(x|s)}}{Z_{k}(s)}$$
(3.27)

Taking logarithms and using Jensen's inequality gives,

$$\ln Z_{k}() \ln Z_{k}(s) + W_{k}(x|s) \mu_{k}(dx|s)$$
(3.28)

From Lemma 3.2a,

$$\limsup_{k} \frac{1}{|k|} \ln Z_{k}(s) \quad P(k,h)$$
(3.29)

Assuming k is sufficiently large and using the same notation as in the proof of Lemma 3.1,

$$Z_{k}(s) = e^{-H_{k}(x|s)}(x) = (dx)$$

$$= e^{-W_{k}(x_{m}|s_{k})}e^{-H_{m}(x)}_{m}(dx)_{k \in m}(dy)$$

$$e^{-n(s)|x_{m}|}\mu_{m}(dx) Z_{m}(x) \qquad (3.30)$$

Thus, using Jensen's inequality again shows

$$\ln Z_{k}(s) \ln Z_{m}(-) - n = |x_{m}| \mu_{m}(dx)$$

Applying Lemma 3.1a gives

$$\frac{1}{|_{k}|} \ln Z_{k}(s) = \frac{|_{m}|}{|_{k}|} \frac{1}{|_{m}|} \ln Z_{m}(-) - n = \frac{|_{m}|}{|_{k}|} g_{1}(-)$$
(3.31)

Thus

$$\liminf_{k} \inf \frac{1}{|_{k}|} \ln Z_{k}(s) = P(, h) - n g_{1}(, h)$$

Since > 0 is arbitrary,

$$\lim_{k} \inf \frac{1}{|k|} \ln Z_{k}(s) \quad P(k, h)$$
(3.32)

Combining (3.32) and (3.29) proves the corollary.

 $\label{eq:Lemma 3.3} \mbox{ Let } be a \mbox{ bounded Borel set}, F \quad \Tilde{B} \ , n \quad \mbox{1 and let } I_1 \mbox{ and } I_2 \mbox{ be closed} \\ intervals \ on \ the \ real \ line \ with \ I_1 \ to \ the \ right \ of \ zero. \ Then \ \label{eq:Lemma 3.3}$ 

a)  $(F \mid s \mid_k)$  ( ,h)  $(F \mid s)$  ( ,h) uniformly for all s  $U_n$  , 1, and h  $I_2$  as k .

b) if  $_L$  for some integer L,  $(H (x) | s _k) (, h)$  (H (x) | s) (, h) uniformly for all s  $U_n$ , 1, as k.

 $exp\{-H (x|s)\} (dx)$   $proof. a) Since (F | s) (,h) = \frac{F}{exp\{-H (x|s)\}} (dx) and Z (s) 1, it suffices to$   $show that exp\{-H (x|s) \ _k)\} (dx) converges uniformly to$   $exp\{-H (x|s)\} (dx) for any G \tilde{B} . Observe that |e^b - e^a| M |b - a| for any M G$ bounding e<sup>x</sup> on an interval containing a and b. Thus, by Lemma 2.1 and Remark 2.2, for any >0, there exist m and k such that m k and for all k sufficiently large,

$$|exp\{-H (x|s)\} - exp\{-H (x|s _k)\}|$$
$$|W_{m}(x |s _{k}^{c})|exp\{ [B+nC\sqrt{\ln m} ]|x _{k}| exp\{ [B+nC\sqrt{\ln m} ]|x |\}.$$

Hence

$$| \exp\{-H (x|s)\} (dx) - \exp\{-H (x|s_{k})\} (dx)| n_{j=0} j \exp\{ [B+nC\sqrt{\ln m}]j\} \frac{|j|}{j!}.$$
(3.33)

|}

The right side of (3.33) is finite and continuous in and h. This completes the proof of part

a.

b) (H (x) | s) - (H (x) | s \_k) = H (x) 
$$\frac{e^{-H (x|s)}}{Z (s)} - \frac{e^{-H (x|s _k)}}{Z (s _k)}$$
 (dx) =

$$[\cdot]_{0} H_{(x)} \left| \frac{e^{-H_{(x|s)}}}{Z_{(s)}} - \frac{e^{-H_{(x|s-k)}}}{Z_{(s-k)}} \right| \quad (dx) - H_{(\cdot]<0} H_{(x)} \left| \frac{e^{-H_{(x|s)}}}{Z_{(s)}} - \frac{e^{-H_{(x|s-k)}}}{Z_{(s-k)}} \right| \quad (dx)$$

$$(3.34)$$

where the symbol [·] in (3.34) represents  $\frac{e^{-H_{(x|s)}}}{Z_{(s)}} - \frac{e^{-H_{(x|s-k)}}}{Z_{(s-k)}}$ . We will calculate

upper and lower bounds for each of the integrals in (3.34).

$$[\cdot]_{0} H_{(x)} \left| \frac{e^{-H_{(x|s)}}}{Z_{(s)}} - \frac{e^{-H_{(x|s-k)}}}{Z_{(s-k)}} \right| \quad (dx)$$

$$\frac{-B^{2}}{2A} | |_{[\cdot] 0} \frac{e^{-H (x|s)}}{Z (s)} - \frac{e^{-H (x|s-k)}}{Z (s-k)} | (dx)$$

$$\frac{-B^{2}}{2A} | |_{[\cdot] 0} \frac{e^{-H (x|s)}}{Z (s)} - \frac{e^{-H (x|s-k)}}{Z (s-k)} (dx) (3.35)$$

The integral in (3.35) converges to zero uniformly in and s  $U_n$  by part a. For an upper bound, observe that for >0,

$$\begin{aligned} H_{[*] 0} H_{(x)} \left| \frac{e^{-H_{(x|s)}}}{Z_{(s)}} - \frac{e^{-H_{(x|s-k)}}}{Z_{(s-k)}} \right| & (dx) \\ &= \frac{1}{e^{-H_{(x|s)}}} H_{(x)} e^{-H_{(x)}} \left| \frac{e^{-W_{(x|s)}}}{Z_{(s)}} - \frac{e^{-W_{(x|s-k)}}}{Z_{(s-k)}} \right| & (dx) \\ &= \frac{1}{e^{-W_{(x|s)}}} \left| \frac{e^{-W_{(x|s)}}}{Z_{(s)}} - \frac{e^{-W_{(x|s-k)}}}{Z_{(s-k)}} \right| & (dx) \\ &\leq \frac{1}{e^{-W_{(x|s-k)}}} \left| \frac{Z_{(s-k)}}{Z_{(s-k)}} \right| \frac{Z_{(s-k)}}{Z_{(s)}} e^{-W_{(x|s-k)}} - 1 \left| -\frac{Z_{(s-k)}}{Z_{(s)}} \right| & (dx) \\ &\leq \frac{1}{e^{-D_{L}(s-k)|x|}} \frac{Z_{(s-k)}}{Z_{(s)}} \left| e^{-W_{(x|s-k)}} - 1 \right| + \left| 1 - \frac{Z_{(s-k)}}{Z_{(s)}} \right| & (dx) \\ &\leq \frac{1}{e^{-nC|x|\sqrt{n+L}}} \frac{Z_{(s-k)}}{Z_{(s)}} - |x|ne^{-|x|n|} + \left| 1 - \frac{Z_{(s-k)}}{Z_{(s)}} \right| & (dx) (3.36) \end{aligned}$$

when k is sufficiently large. A routine calculation now shows that (3.36) can be made arbitrarily small for all s  $U_n$  and  $I_1$  by choosing k sufficiently large (and sufficiently small).

The second integral in (3.34) has the same upper and lower bounds. It follows that (3.34) convergers uniformly to zero as k .

**Theorem 3.1** Let  $Q = Q_0 = k = 1$  be the unit cube centered at the origin.

a) The expectation

$$H_Q(x) + \frac{1}{2} W_Q(x|x_{Q^c}) \mu(dx)$$
 (3.37)

is the same for any translation invariant, tempered Gibbs state  $\mu$  for H,  $_{O}$  h, if and only if P(, h) is continuously differentiable at  $_{0}$ .

b) The expectation

 $|x \quad Q| \quad \mu(dx)$ 

is the same for any translation invariant, tempered Gibbs states  $\mu$  for H, , h<sub>0</sub>, if and only if P( , h) is continuously differentiable at h<sub>0</sub>.

*Remark 3.2.* Theorem 3.1 may be modified. In equation (2.1), one may assume, if desired, that  $h = \frac{\hat{h}}{-}$  for some "chemical potential"  $\hat{h}$  independent of . In this way h is independent of . With this convention, is the coefficient of the particle interaction energy and h is, independently, the coefficient of the particle number in P( , h). Note also that  $H_Q(x) + \frac{1}{2} W_Q(x|x_{Q^c}) \mu(dx) = \lim_k \frac{1}{|k|} H_k(x) \mu(dx)$  by translation invariance of  $\mu$  and Lemma 3.2, so that part a of the Theorem 3.1 may be reformulated. The restriction that Q = -1, the unit cube, in Theorem 3.1 may be relaxed. Q can be chosen to be any geometric solid whose translates partition  $\mathbf{R}^d$ , such as a rectangular solid. The underlying lattice  $\mathbf{Z}^d$  must then be replaced with another lattice, -k then becomes a union of translates of Q for each k, U is then changed, etc.

Proof.

a) Since P ( ,h) is a convex function of , P is differentiable on a dense subset of the positive real line. Suppose that P is differentiable at . For any k,  $\frac{1}{|k|} \ln Z_k(s)$  is convex and differentiable with respect to for any s U . From Cor. 3.1, it follows that for any point where P is differentiable,

$$\frac{\mathrm{dP}}{\mathrm{d}} = \lim_{k} \frac{1}{|k|} \quad H_{k}(x|s) \ \mu_{k}(\mathrm{d}x|s)$$

Let  $\mu$  be a translation invariant, tempered Gibbs state. From the Lebesgue Dominated

Convergence Theorem and Lemma 3.1 we have

$$\frac{dP}{d} = \lim_{k} \frac{1}{|k|} \qquad H_{k}(x|s) \mu_{k}(dx|s) \mu(ds)$$

By the definition of a Gibbs state, dP ... 1

$$\frac{\mathrm{d}P}{\mathrm{d}} = \lim_{k} \frac{1}{|x|} \quad \mathrm{H}_{k}(\mathbf{x}|\mathbf{x}_{k}) \mu(\mathrm{d}\mathbf{x})$$

By Lemma 3.2,

$$\frac{dP}{d} = \lim_{k} \frac{1}{|_{k}|} H_{k}(x) \mu(dx)$$
(3.38)

Now write

$$H_{k}(x) = [H_{Q_{i}}(x) + \frac{1}{2}W(x_{Q_{i}}|x_{Q_{i}^{c}}]]$$
  
= 
$$[H_{Q_{i}}(x) + \frac{1}{2}W(x_{Q_{i}}|x_{Q_{i}^{c}}] - \frac{1}{2}W(x_{k}|x_{k}])$$
(3.39)

where the sums are over all i such that  $Q_i = k$ . Combining (3.38) and (3.39) and using the translation invariance of  $\mu$  gives

$$\frac{dP}{d} = H_Q(x) + \frac{1}{2} W(x_Q | x_{Q^c}) \mu(dx) - \frac{1}{2} \lim_{k} \frac{W(x_k | x_{Q^c})}{|x_k|} \mu(dx)$$
(3.40)

From Lemma 3.2

$$\frac{dP}{d} = H_Q(x) + \frac{1}{2} W(x_Q | x_{Q^c}) \mu(dx)$$
(3.41)

Thus (3.37) is the same for all translation invariant Gibbs states if P is differentiable at  $_0$ .

Let

$$g(x) = H_Q(x) + \frac{1}{2}W(x_Q|x_{O^c})$$
(3.42)

and let  $\{ m\}$  be chosen so that m = 0 and such that P(, h) is differentiable at each m. Let  $\frac{d^{T}P}{d}$  and  $\frac{d^{T}P}{d}$  denote respectively right and left hand derivatives of P (see Remark 2.1).

Then

$$\frac{d^{r}P}{d}(0,h) \lim_{m} \frac{dP}{d}(m,h)$$

$$=\lim_{m} g(x)\mu_{m}(dx)$$
(3.43)

by (3.41) where  $\mu_m$  is a translation invariant, tempered Gibbs state for H, h, m.

The next step is to show that for some subsequence of  $\{\mu_m\}$  which we again denote by  $\{\mu_m\},$ 

$$\lim_{m} g(x)\mu_{m}(dx) = g(x)\mu(dx)$$
(3.44)

where  $\mu$  is a translation invariant, tempered Gibbs state for H, <sub>0</sub>, h. Then by (3.43) and (3.44),

$$\frac{d^{r}P}{d}(_{0},h) = g(x)\mu(dx)$$
 (3.45)

An analogous inequality bounding  $\frac{d^{T}P}{d}(_{0}, h)$  below, together with the assumption that g(x) has the same expectation with respect to any translation invariant Gibbs state at  $_{0}$  will prove that P is continuously differentiable at  $_{0}$ .

Let 
$$\tilde{A}$$
 be the countable field given by Prop 2.3 for the -field  $\tilde{B}$ . Define  
 $\tilde{A} = \bigcup_{k} \tilde{A}_{k}$ 
(3.46)

Since  $\tilde{A}$  is countable, some subsequence of  $\{\mu_m\}$ , which we again denote by  $\{\mu_m\}$  converges for each element of  $\tilde{A}$ . Define  $\mu(A)$  by

$$\mu(A) = \lim_{m} \mu_m(A) \tag{3.47}$$

By Prop. 2.3, for any fixed k,  $\mu$  has a unique extension to  $\tilde{B}_{k}$  which we again denote by  $\mu$ . Let F  $\tilde{B}_{k}$  and s U. Recall that F'={x X():x s F} and in this case F' is independent of s. Then

$$(F|s) = \exp\{-H_{k}(x|s)\}_{k}(dx)$$

$$\exp\{-\frac{A}{|k|}|x|^{2} + (B + n(s)C\sqrt{\ln_{k}k})|x|\}_{k}(dx)$$

$$\max = \exp\{-\frac{A}{|k|}|x|^{2} + (B + n(s)C\sqrt{\ln_{k}k})|x|\}:|x| = R_{k}(F)$$

$$M(-,h,k,n(s)) = (F)$$

$$(3.48)$$

where we have used Remark 2.2, superstability, the observation that  $Z_{(s)} = 1$  for all s and , and



It follows from (3.48) that {  $(F|s)(m,h): m = 1,2,3,..., and s U_n$ }, where 0 as above, is uniformly absolutely continuous with respect to the measure on  $\tilde{B}_{,}$  given by

 $_{k}(F)$   $_{k}(F)$ , i.e., given any >0, there exists a >0 (depending on n) such that  $_{k}(F|s) (m,h) <$ for all m and s  $U_{n}$  whenever  $_{k}(F) <$ .

From Prop. 2.1 all tempered Gibbs states for a given value of and h satisfy Ruelle's estimates for the same values of and . It follows from the proofs in Ref. 9 that the same values of and may be selected for the entire sequence of tempered Gibbs states  $\{\mu_m\}$  given in (3.43) corresponding to  $\mu_m = 0$  (in fact, =(-0 A)/4 may be used).

Let >0 be given. Choose n so that  $\mu_m(U_n^c) < /2$  for all m. Choose >0 so that (F|s)(m,h) < /2 whenever  $k(F) < and s U_n$ . Then

$$\mu_{m}(F) = \mu_{m}( \sum_{k} (F|s) (m,h))$$

$$= \sum_{U_{n} \in V_{n}} (F|s)(m,h) \mu_{m}(ds) + \sum_{U_{n}^{c} \in V_{n}} (F|s)(m,h) \mu_{m}(ds)$$

$$< \frac{1}{2} + \frac{1}{2} = (3.49)$$

Thus given any k, the measures  $\{\mu_m\}$  restricted to  $\tilde{B}_{k}$  are uniformly absolutely continuous with respect to k.

Let  $\mathbf{R}^d$  be a bounded Borel set and let  $F \quad \tilde{B}$ . Without loss of generality, we may assume  $=_k$  for some k. Let > 0 and choose as in (3.49). Since  $(\tilde{A}) = \tilde{B}$ , there exists an A  $\tilde{A}$  such that  $\mu(A \mid F) <$  and  $_k(A \mid F) <$ . Here A  $F = (A \setminus F)$  (F\A).

By the triangle inequality,

$$|\mu_{m}(F) - \mu(F)| \quad |\mu_{m}(A) - \mu(A)| + \mu_{m}(A - F) + \mu(A - F)$$

$$|\mu_{m}(A) - \mu(A)| + 2$$
(3.50)

It follows that

$$\mu(\mathbf{F}) = \lim_{m} \mu_{\mathbf{m}}(\mathbf{F}) \tag{3.51}$$

for all F  $\tilde{B}$ . Equation (3.51) shows that  $\mu(F)$  is consistently defined on the increasing

sequence of - fields { $\tilde{B}_{k}$ }. Since these - fields generate the - field S,  $\mu$ has a unique extension (e.g. by Kolmogorov's Theorem) to a probability measure on (-, S) which we again denote by  $\mu$ . The translation invariance of  $\mu$  follows from the translation invariance of  $\mu_{m}$  and standard arguments in measure theory.

We next prove that  $\mu$  is a Gibbs state for  $_{O}$  H, h. It is routine to verify that

$$(F | s) (m,h)$$
  $(F | s) (Oh)$  (3.52)

for each s U, each, and each measurable set F. By the triangle inequality,

$$\begin{aligned} |\mu_{n}((F \mid s) (m,h)) - \mu((F \mid s) (Oh))| \\ & |\mu_{n}[(F \mid s \mid s) (m,h)) - \mu((F \mid s \mid s) (Oh))| \\ & + |\mu_{m}[(F \mid s) (m,h) - (F \mid s \mid s) (M,h)| \\ & + |\mu[(F \mid s) (Oh) - (F \mid s \mid s) (Oh)]| \end{aligned}$$
(3.53)

It follows from Lemma 3.3 and arguments similar to those leading to (3.49) that by choosing k sufficiently large, the last two terms on the right side of (3.53) can made arbitrarily small, uniformly in m. By Prop. 2.2 and (3.52) the first term on the right side of (3.53) converges to zero as m for any fixed k.

Thus

$$\mu_{m}((F \mid s) (m,h)) \quad \mu((F \mid s) (Oh))$$

Since we also have

 $\mu_m((F \mid s) (m,h)) = \mu_m(F) (F)$ 

for any cylinder set F, it follows that  $\mu$  is a Gibbs state. It is easy to check that  $\mu$  is tempered using the fact the same constants and may be used for each  $\mu_m$ .

It remains to verify (3.44). Let

i

$$g_{Q_i}(x) = H_{Q_i}(x) + \frac{1}{2} W(x_{Q_i}|x_{Q_i})$$

For a given positive integer L, let L. Then, as in (3.39)

$$g_{Q_i}(x) = H(x) + \frac{1}{2}W(x | x_c)$$

Therefore

$$\mu( g_{Q_i}(x)) = | | \mu(g) = \mu(H_i(x)) + \frac{1}{2}\mu(W(x_i|x_{c}))$$

and hence

$$\mu(g) = \frac{1}{|||} \mu(H_{(x)}) + \frac{1}{2} \frac{1}{|||} \mu(W(x_{(x)}))$$

for any translation invariant tempered Gibbs state µ. Thus

$$\begin{aligned} |\mu_{m}(g) - \mu(g)| &= \frac{1}{||} |\mu(H_{-}) - \mu_{m}(H_{-})| \\ &+ \frac{1}{2} |\mu(\frac{W(x_{-}|x_{-})}{|||}) - \mu_{m}(\frac{W(x_{-}|x_{-})}{||||})| \end{aligned}$$
(3.54)

We first show

$$\frac{1}{||}\mu_{m}(H) = \frac{1}{|||}\mu(H)$$
(3.55)

for any L ( L) by proving that

 $\mu_{m}((H | s) (m,h)) \quad \mu((H | s) (Oh))$ (3.56)

In all that follows, h will be fixed and we therefore omit it from the notation.

$$\begin{aligned} |\mu_{m}( (H | s) (m) - \mu( (H | s) (O) | \\ & |\mu_{m}( (H | s k) (m) - \mu( (H | s k) (O) | \\ & + |\mu_{m}( (H | s) (m) - \mu_{m}( (H | s k) (O) | \\ & + |\mu( (H | s) (O) - \mu( (H | s k) (O) | \\ & + |\mu( (H | s) (O) - \mu( (H | s k) (O) | \\ & + |\mu( (H | s) (O) - \mu( (H | s k) (O) | \\ & + |\mu( (H | s) (O) - \mu( (H | s k) (O) | \\ & + |\mu( (H | s) (O) - \mu( (H | s k) (O) | \\ & + |\mu( (H | s) (O) - \mu( (H | s k) (O) | \\ & + |\mu( (H | s) (O) - \mu( (H | s k) (O) | \\ & + |\mu( (H | s) (O) - \mu( (H | s k) (O) | \\ & + |\mu( (H | s) (O) - \mu( (H | s k) (O) | \\ & + |\mu( (H | s) (O) - \mu( (H | s k) (O) | \\ & + |\mu( (H | s) (O) - \mu( (H | s k) (O) | \\ & + |\mu( (H | s) (O) - \mu( (H | s k) (O) | \\ & + |\mu( (H | s) (O) - \mu( (H | s k) (O) | \\ & + |\mu( (H | s) (O) - \mu( (H | s k) (O) | \\ & + |\mu( (H | s) (O) - \mu( (H | s k) (O) | \\ & + |\mu( (H | s) (O) - \mu( (H | s k) (O) | \\ & + |\mu( (H | s) (O) - \mu( (H | s k) (O) | \\ & + |\mu( (H | s) (O) - \mu( (H | s k) (O) | \\ & + |\mu( (H | s) (O) - \mu( (H | s k) (O) | \\ & + |\mu( (H | s) (O) - \mu( (H | s k) (O) | \\ & + |\mu( (H | s) (O) - \mu( (H | s k) (O) | \\ & + |\mu( (H | s) (O) - \mu( (H | s k) (O) | \\ & + |\mu( (H | s) (O) - \mu( (H | s k) (O) | \\ & + |\mu( (H | s) (O) - \mu( (H | s k) (O) | \\ & + |\mu( (H | s) (O) - \mu( (H | s k) (O) | \\ & + |\mu( (H | s) (O) - \mu( (H | s k) (O) | \\ & + |\mu( (H | s) (O) - \mu( (H | s k) (O) | \\ & + |\mu( (H | s) (O) - \mu( (H | s k) (O) | \\ & + |\mu( (H | s) (O) - \mu( (H | s k) (O) | \\ & + |\mu( (H | s k) (O) - \mu( (H | s k) (O) | \\ & + |\mu( (H | s k) (O) - \mu( (H | s k) (O) | \\ & + |\mu( (H | s k) (O) - \mu( (H | s k) (O) | \\ & + |\mu( (H | s k) (O) - \mu( (H | s k) (O) | \\ & + |\mu( (H | s k) (O) - \mu( (H | s k) (O) | \\ & + |\mu( (H | s k) (O) - \mu( (H | s k) (O) | \\ & + |\mu( (H | s k) (O) - \mu( (H | s k) (O) | \\ & + |\mu( (H | s k) (O) - \mu( (H | s k) (O) | \\ & + |\mu( (H | s k) (O) - \mu( (H | s k) (O) | \\ & + |\mu( (H | s k) (O) - \mu( (H | s k) (O) | \\ & + |\mu( (H | s k) (O) - \mu( (H | s k) (O) | \\ & + |\mu( (H | s k) (O) - \mu( (H | s k) (O) | \\ & + |\mu( (H | s k) (O) - \mu( (H | s k) (O) | \\ & + |\mu( (H | s k) (O) - \mu( (H | s k) (O) | \\ & + |\mu( (H | s k) (O) - \mu($$

or L sufficiently large, using the notation of Lemma 3.1,  $\frac{1}{|||} | (H | s) ()| = \frac{1}{|||} | [H (x|s) - W (x|s)] \mu (dx|s) |$   $g_2(s) + g_3(s)$ (3.58)

It follows from the proof of Lemma 3.1, that we may choose (since  $n(s \ k) \ n(s)$ )

 $g_i(s \ k) \ g_i(s)$  for all k, s U, and i = 1,2,3. Since, in addition each  $g_i$  is a polynomial in and a polynomial in n(s),

 $| (H | s) (_{m}) - (H | s _{k}) (_{m})| G(s)$ (3.59)

where G(s) is a polynomial in n(s) and is independent of m.

Since the same constants and may be used for each  $\mu_m$ ,

$$\underset{U_{N}^{c}}{n(s)^{j}} \mu_{m}(ds) \qquad \ell^{j} \mu_{m}(U_{\ell-1}^{c})$$
 (3.60)

converges to zero uniformly in m as N  $\,$ , for any j (c.f. (3.11)). Then for any >0, there exists an integer N  $\,$ 1 such that

$$G(s) \mu_{\rm m}(ds) < (3.61)$$

for all m. We may also assume (3.61) holds when  $\mu_m$  is replaced by  $\mu$ . Then the second term on the right side of (3.57) may be bounded as follows:

$$|\mu_{m}((H \mid s) (m) - \mu_{m}((H \mid s k) (m))|$$

$$| [ (H | s) (_{m}) - (H | s _{k}) (_{m})] \mu_{m}(ds)| + G(s) \mu_{m}(ds)$$
(3.62)

It follows by (3.61) and Lemma 3.3b that the right side of (3.62) may be bounded uniformly in m by an arbitrarily small number, when k is chosen sufficiently large. The third term on the right side of (3.57) is similarly bounded.

Following essentially the same argument as above, leading to (3.58) and (3.61), there exists a function F(s k) independent of m, such that

 $| (H | s _{k}) (m) | F(s _{k})$  (3.63)

and (3.61) is satisfied when G(s) is replaced by F(s = k).

Given any >0, there is an integer N 1 such that  $F(s_k)$  is the sum of a bounded measurable cylinder function, namely its restriction to  $U_N$ , and an unbounded function (its restriction to  $U^c_N$ ) such that the integral of the latter function with respect to  $\mu$  or  $\mu_m$  is less than uniformly in m. A simple application of the triangle inequality and (3.51) shows that

$$\mu_{\rm m}(F(s \ k)) \quad \mu(F(s \ k)) \tag{3.65}$$

for any k. Combining (3.65), (3.63), and Prop.2.2 proves that the first term on the right side of (3.57) can be made arbitrarily small for any given k, by choosing m sufficiently large. Thus (3.56) and (3.55) are proved.

We next show that by choosing L sufficiently large, the second term on the right side of (3.54) can be made arbitrarily small, uniformly in m. Since the arguments for this are similar to those given above, we provide only an outline.

The second term on the right side of (3.54) equals

$$\frac{W_{(x|s)}}{| | |} \mu_{(dx|s)} \mu_{m}(ds) - \frac{W_{(x|s)}}{| | |} \mu_{(dx|s)} \mu(ds) \left| (3.66) \right|$$

where we have suppressed the dependence of  $\mu$  (dx|s) on m or 0. Given N 1, it follows from (3.15) and (3.24) that the integral

$$\frac{W_{L}(x|s)}{|L|} \mu (dx|s)(m)$$

converges to zero uniformly in m and s  $U_N$ , as L . From the proof of Lemma 3.1, it follows that there exists a function P(s) such that

$$| \frac{W_{L}(x|s)}{|_{L}|} \mu (dx|s)(_{m})| P(s)$$
 (3.67)

for all L sufficiently large and all m such that (3.61) is satisfied when G(s) is replaced by P(s). An application of the triangle inequality now shows that (3.66) converges to zero as L , uniformly in m.

Thus the right side of (3.54) can be made arbitrarily small by first choosing L and then m sufficiently large. Equation (3.44) is now established. This completes the proof of part a.

b) Suppose P is differentiable at h. Then for any s U,

$$\frac{dP}{dh} = \lim_{k} \frac{1}{||_{k}|} \frac{d}{dh} [H_{k}(x|s)] \mu_{k}(dx|s)$$
$$= \lim_{k} \frac{d}{||_{k}|} |x_{k}| \mu_{k}(dx|s)$$
(3.68)

Let  $\mu$  be a translation invariant, tempered Gibbs state. From the Lebesgue Dominated Convergence Theorem and Lemma 3.1,

$$\frac{dP}{dh} = \lim_{k} \frac{|x|}{|x|} |x| + |\mu_{k}(dx|s) \mu(ds)$$

$$= \lim_{k} \frac{|x|}{|x|} |x| + |\mu(dx)$$

$$= |x| Q| \mu(dx)$$
(3.69)

The rest of the proof of b) follows as in part a) with the cylinder function  $|x_Q|$  playing the role of g(x) and h playing the role of  $\$ .

*Remark 3.3* Theorem 3.1 may be extended to deal with Gibbs states invariant under groups which preserve the algebra of measurable cylinder sets, other than the translation group on  $\mathbf{R}^d$ . For example, let G be a group of Euclidean motions on  $\mathbf{R}^d$  containing a subgroup of the translation group. Assuming that Gibbs states invariant under G exist for each and h, the proof of Theorem 3.1 may be modified to show that the pressure is differentiable with respect to (resp. h) if and only if all Gibbs states invariant under G yield the same expected specific energy (resp. density of particles). Theorem 3.1 may be easily extended to lattice systems and groups preserving the lattice and the algebra of measurable cylinder sets. For  $G = \mathbf{Z}^d$  the lattice version of Theorem 3.1 is an easy consequence of Ref. 6 (see also Refs.7, 3).

The following corollary is now immediate.

**Corollary 3.2** Suppose the Gibbs state for H,  $_0$ ,  $h_0$  is unique. Then the pressure p( ,h) is continuously differentiable with respect to  $\$ and with respect to h at (  $_0$ ,  $h_0$ ).

Corollary 3.3 below follows from the proof of Theorem 3.1.

**Corollary 3.3** Let  $\mu_m$  be a translation invariant, tempered Gibbs state for , m, h and suppose m 0 > 0. Then the sequence { $\mu_m$ } has a subsequence whose limit on any cylinder set F is  $\mu(F)$ , where  $\mu$  is a translation invariant, tempered Gibbs state for , 0, h. An analogous statement holds when h<sub>m</sub> h, and is fixed.

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